# Smarthome Design Using Raspberry Pi 3 Based on Internet Of Things (IoT)

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#### **ABSTRACT**

Advances in Internet of Things (IoT) technology have driven the development of smart, efficient, and widely accessible home automation systems. This study aims to determine how to design and integrate Raspberry Pi technology with Bylnk to control relays remotely manually using widgets and automatically using LDR and DHT11 sensors. The research method employs an engineering research approach focused on the design, development, and testing of a prototype smart home system based on the Internet of Things (IoT) using Raspberry Pi 3. The process begins with a literature review on IoT concepts and Raspberry Pi characteristics, followed by the design of hardware and software that integrates the Raspberry Pi 3, LDR and DHT11 sensors, a four-channel relay module, and the Blynk platform for the user interface. After assembly, the system is tested through experimental scenarios observing LED responses to four input conditions: light intensity, ambient temperature, automatic timer, and manual commands via the Blynk app. The collected data is quantitative observational, including LED status (on/off), response time, and analyzed descriptively and comparatively by comparing actual results against the success criteria established in the design. The test results show that the system operates reliably in executing each control function, both automatic and manual, with fast and accurate responses. This research contributes to the development of a modular, cost-effective, and easily implementable smart home system in real residential environments.

Keywords: Smart home, Internet of Things (IoT), Raspberry Pi 3, Blynk

#### Introduction

Science and technology (IPTEK) is advancing rapidly, especially in the field of engineering technology. One example of a technology that has been widely developed is the Internet of Things (IoT), which can connect all devices to the internet and enable them to communicate with each other via the internet [1]. To support this, remote control is needed. Currently, Raspberry Pi 3 is the technology that can meet this need [2].

Outdoor activities often make it difficult to control and monitor electrical appliances in the home [3]. Humans are highly dependent on electricity, making it one of the basic necessities of life. It is common to find situations where homeowners forget to turn off the lights when they are outside the house, forcing them to return and conduct an inefficient check—both in terms of time and finances, such as the cost of gasoline to return home again [4].

Research on the design of smart homes using Raspberry Pi 3 based on the Internet of Things (IoT) to improve security and efficiency has been widely conducted. Research by Kusuma, dkk. developed an internetconnected home door security system with RFID and sensor features for real-time monitoring [5]. Surya Angga Pranata, dkk. designed a tool for detecting illegal logging using sound sensors and cameras with notifications sent to Telegram [6]. Andrian, dkk. built a mobile-based remote lighting control system using Raspberry Pi and Python. Meanwhile [7], Ayyina Dewi Parwati, dkk. designed a smart camera that can monitor an area and send automatic alerts to a smartphone [8]. Based on previous studies, such as home door security systems, illegal logging detectors, simple light controllers, and Raspberry Pi-based smart cameras, most focus on a specific function or limited use without integrating various sensors comprehensively into a single system. Additionally, there have been few studies that comprehensively combine automatic and manual control for household devices, particularly in time-, light-, and temperature-based lighting control integrated through the Blynk platform and Raspberry Pi 3. This highlights the need for the development of a more functional, flexible, and responsive smart home system that can adapt to various environmental conditions and be easily controlled remotely.

The development of the Internet of Things (IoT) concept aims to create efficient and automatic connections between various objects. The Internet of Things (IoT) works by connecting various electrical devices over any distance without user intervention. The Internet of Things (IoT) has developed innovations such as smart homes, where this technology is used as an automated control system to manage electronic devices in homes and offices via the internet [9]. Blynk is a platform that supports the control of Arduino, Raspberry Pi, ESP8266, WEMOS D1, and similar modules via the internet. Blynk is a platform for creating

graphical interfaces for projects that can be implemented using a drag-and-drop widget method, making it very easy to use [10]. This study designed and built a smart home prototype that integrates Raspberry Pi 3 with the Blynk platform and light, temperature, and time sensors to create an automated and remote control system for electrical appliances, particularly lights. This system not only relies on manual control via an application but also operates automatically to adapt to environmental conditions, making it more efficient and adaptive to user needs. By integrating various technologies into a unified system, this research offers an innovative solution to the challenges users often face when monitoring and controlling electrical devices while away from home.

Based on the above explanation, a study was conducted to answer how to design and build a simple smart home prototype, but focused on the needs of performing many tasks that hinder movement to turn lights on or off remotely, as well as adding automatic sensors such as light, temperature, and time sensors. To create this concept, a device is needed that can control like a remote control but with unlimited range. In this study, the researcher utilized Bylnk technology combined with a Raspberry Pi 3 as the main controller to ensure the desired concept functions effectively and connects it to the internet to enable control without limitations on distance or location.

#### **Research Methods**

This research method applies an engineering research approach that focuses on the design, construction, and testing of a smart home system prototype based on the Internet of Things (IoT) using Raspberry Pi 3. The process begins with a literature review on IoT concepts and Raspberry Pi characteristics, followed by the design of hardware and software that integrates the Raspberry Pi 3, LDR and DHT11 sensors, a four-channel relay module, and the Blynk platform for the user interface. After assembly, the system is tested through experimental scenarios observing LED responses to four input conditions: light intensity, ambient temperature, automatic timer, and manual commands via the Blynk app. The collected data is quantitative observational, including LED status (on/off), response time, and analyzed descriptively and comparatively by comparing actual results against the success criteria established in the design.



Figure 1 Research Diagram

Figure 1 below is a flowchart of the research or development process for an Internet of Things (IoT)based device. The process begins with an initial stage of literature review to gather relevant information and references as a basis for device design. Following this, device design is carried out, which includes component assembly and system programming. The designed device then enters the testing phase to verify its functionality. If the testing results are unsuccessful, improvements are made by returning to the design phase. However, if the testing is successful, the process continues with synchronization to the Blynk application so that the device can be controlled and monitored in real-time via a smartphone. Once synchronization is complete and the system functions properly, the research process is deemed complete.



Figure 2 Smarthome System and Architecture

Figure 2 shows the architecture of an Internet of Things (IoT)-based monitoring and control system that utilizes Raspberry Pi as the control center. This system consists of several main components, namely sensors, Raspberry Pi, relay modules, LEDs, and the Blynk application connected via a smartphone. LDR and DHT11 sensors are used to detect light intensity, temperature, and humidity. Data from the sensors is sent to the Raspberry Pi for analysis, which then controls the relay module based on the data. The relay subsequently controls the LED to turn on or off as an indicator. Additionally, the Raspberry Pi is connected to a Wi-Fi network and can communicate with the Blynk app, enabling users to monitor environmental conditions and control the LED directly via a smartphone.



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4	GPIO15	IN2 (Relay)
5	GPIO23	IN3 (Relay)
6	GPIO24	IN4 (Relay)
7	3V3	VCC (DHT11)
8	GND	GND (DHT11)
9	GPIO4	DAT (DHT11)
10	5V	VCC (LDR)
11	GND	GND (LDR)
12	GPIO17	DO(LDR)

Figure 3 and Table 1 illustrate the wiring diagram for the entire home automation circuit. For the 4channel relay module, the relay's VCC pin is connected to the Raspberry Pi's 5V pin to supply power, and the relay's GND pin is connected to the Raspberry Pi's GND pin. The four relay control pins—IN1, IN2, IN3, and IN4—are each connected to the Raspberry Pi's GPIO pins, namely GPIO14, GPIO15, GPIO23, and GPIO24. These pins are used to control each relay channel. Next, for the DHT11 temperature and humidity sensor, the DHT11 VCC pin is connected to the Raspberry Pi's 3.3V pin, while the DHT11 GND is connected to the Raspberry Pi's GND pin. The DHT11 sensor's data pin, DAT, is connected to the Raspberry Pi's GPIO4 pin to read temperature and humidity data. Finally, for the digital LDR light sensor, the LDR's VCC pin is connected to the Raspberry Pi's 5V pin, and the LDR's GND pin is connected to the Raspberry Pi's GND pin. The digital output from the LDR sensor (DO pin) is connected to the Raspberry Pi's GPIO17 pin to read the lighting conditions (bright or dark).



#### Figure 4 System Flowchart

Figure 4 shows the workflow of the Raspberry Pi-based automatic and manual LED light control system with sensor integration and the Blynk application. The system starts with two control options: manual control and automatic control. In manual control mode, the user first logs into the Blynk application, then uses the control widget to turn the LED on or off. If the user activates the control, the relay will turn the LED on or off, and the Raspberry Pi will send the LED status to the Blynk server, so that the user can view the status through the application. This process ends after Blynk receives the data packet.

Meanwhile, in automatic control mode, the system utilizes three main parameters, namely light, temperature, and time [11]. An LDR sensor is used to read light conditions. If the detected light condition is dark, the relay will turn on the LED. If not, the LED remains off and the LDR returns to reading the light condition. For temperature readings, the system uses a DHT11 sensor. If the detected temperature is below 30°C, the LED will be turned on. If not, the LED remains off, and the DHT11 will resume temperature readings. Finally, for time control, the system processes the predefined time interval of 5 seconds. If this time is reached, the LED will be turned on. If not, the LED remains off until the predefined time is reached again.

## Results

## **Results and Discussion**

Hardware Implementation

The hardware assembly for designing the smarthome in this study was carried out based on the schematic circuit configuration shown in Figure 3.



Figure 5 System Prototype



Figure 6 Prototype Implementation Diagram

Figure 5 shows the physical appearance of the designed system, while Figure 6 shows the implementation diagram of the designed system. This system uses a Raspberry Pi 3 microcontroller as the main control unit, equipped with a 4-channel relay module that functions to regulate the flow of electric current to the LED load. Additionally, an LDR sensor is used to detect ambient lighting conditions (bright or dark), and a DHT11 sensor is employed to monitor the air temperature around the device.

In this prototype, there are four LEDs, each controlled by a different mechanism:

- 1. LED 1 is automatically controlled based on the readings from the LDR sensor. The LED will turn on when the sensor detects low light conditions and will turn off again when bright conditions are detected.
- 2. LED 2 is automatically controlled based on the temperature read by the DHT11 sensor. The LED will turn on when the temperature exceeds 30°C and will turn off when the temperature drops below that threshold.
- 3. LED 3 is controlled using an automatic timer system, which turns it on for 5 seconds and then off for 5 seconds in a repeating cycle.
- 4. LED 4 is manually controlled via the Blynk app connected to the Raspberry Pi 3, allowing users to control the LED remotely using a smartphone.

### **Software Implementation**

The software uses a Raspberry Pi 3 controlled via the Internet of Things (IoT) with the Blynk application. The program is written in Python with supporting modules such as RPi.GPIO for GPIO pin control, Adafruit\_DHT for the DHT11 temperature sensor, and BlynkLib for communication with the Blynk application.

### **GPIO Initialization and Configuration**

The program initializes the Raspberry Pi GPIO pins that will be used to control four LEDs via relays, as well as read inputs from a light sensor (LDR) and a DHT11 temperature sensor.

```
Start the program
Disable GPIO warnings
Set GPIO mode to BCM numbering
Define GPIO pins:
                                 (Output for light sensor)
    LED CAHAYA
                    \leftarrow GPIO 14
    LED SUHU
                    \leftarrow GPIO 15
                                 (Output for temperature sensor)
    LED TIMER
                    ← GPIO 23
                                 (Output for automatic timer)
    LED MANUAL
                    \leftarrow GPIO 24
                                 (Output for manual control via Blynk)
```

```
SENSOR_CAHAYA ~ GPIO 17 (Input from digital light sensor/LDR)
    SENSOR SUHU
                  ← GPIO 4
                               (Input from temperature sensor DHT11)
Set GPIO pin modes:
    Set LED CAHAYA as OUTPUT
    Set LED SUHU as OUTPUT
    Set LED_TIMER as OUTPUT
    Set LED MANUAL as OUTPUT
    Set SENSOR CAHAYA as INPUT
Set all LEDs to initial OFF state:
    LED CAHAYA \leftarrow LOW
    LED SUHU
                \leftarrow LOW
    LED TIMER ← LOW
    LED MANUAL \leftarrow LOW
```

### Initializing Blynk

The program uses authentication tokens from Blynk to connect the Raspberry Pi to the cloud-based Blynk application.

```
Start the program
Import the Blynk library
Store the Blynk authentication token in a variable:
    BLYNK_AUTH ← 'T6YesasbjImjfknc3WR6He406pb0EU2d'
Connect to the Blynk server using the following information:
    - Authentication token: BLYNK_AUTH
    - Server: blynk.cloud
    - Port: 80
```

### LED Control with Blynk Virtual Pins

Manually control LEDs through the Blynk app using virtual pins 0 to 3. Any change in the value of a virtual pin will change the status of the associated LED.

```
If the Blynk application sends data to Virtual Pin V0:
    If the value ≠ 0:
        Turn ON the light sensor LED
        Display "Cahaya ON"
    If the value = 0:
        Turn OFF the light sensor LED
        Display "Cahaya OFF"
If the Blynk application sends data to Virtual Pin V1:
    If the value ≠ 0:
        Turn ON the temperature LED
        Display "Suhu ON"
    If the value = 0:
        Turn OFF the temperature LED
```

```
Display "Suhu OFF"
```

```
If the Blynk application sends data to Virtual Pin V2:
    If the value ≠ 0:
        Turn ON the timer LED
        Display "Timer ON"
    If the value = 0:
        Turn OFF the timer LED
        Display "Timer OFF"
If the Blynk application sends data to Virtual Pin V3:
    If the value ≠ 0:
        Turn ON the manual LED
        Display "Manual ON"
    If the value = 0:
        Turn OFF the manual LED
        Display "Manual OFF"
```

### Light Sensor Monitoring (LDR)

The LDR sensor is connected to the digital GPIO pin. The data received is HIGH or LOW, indicating light or dark conditions. LED 1 is automatically controlled based on this light sensor.

```
Function: monitor_light_sensor
Repeat continuously:
    If the light sensor detects a bright condition:
        Display "Bright! LED OFF"
        Turn OFF the light LED (set GPIO pin to HIGH)
    If the sensor detects a dark condition:
        Display "Dark! LED ON"
        Turn ON the light LED (set GPIO pin to LOW)
    Wait for 1 second before repeating
```

### **DHT11 Temperature Sensor Control**

The DHT11 temperature sensor is read every 2 seconds. If the temperature exceeds a certain limit (30°C), LED 2 will light up as an indicator.

```
Import the DHT11 sensor library
Set the temperature sensor to use:
   DHT_SENSOR ← DHT11
Set the temperature threshold:
   TEMPERATURE_LIMIT ← 30°C
Function: kontrol_suhu
   Repeat continuously:
```

```
Read temperature and humidity data from the DHT11 sensor

If temperature reading is successful:

    Display the temperature and humidity values

    If temperature ≥ TEMPERATURE_LIMIT:

        Turn ON the temperature LED (set GPIO to HIGH)

        Display "Hot! LED ON"

    If temperature < TEMPERATURE_LIMIT:

        Turn OFF the temperature LED (set GPIO to LOW)

        Display "Cool! LED OFF"

If temperature reading fails:

        Display "Failed to read temperature sensor!"

Wait for 2 seconds before repeating
```

### Automatic LED Timer (LED 3)

LED 3 turns on and off alternately every 5 seconds using time.sleep() in an infinite loop.

```
Function: toggle_timer
Repeat continuously:
   Turn ON the timer LED (set GPIO to HIGH)
   Display "LED ON for 5 seconds"
   Wait for 5 seconds

   Turn OFF the timer LED (set GPIO to LOW)
   Display "LED OFF for 5 seconds"
   Wait for 5 seconds
```

### **Starting Programs and Running Threads**

The sensor and timer functions are run in separate threads so that they run in parallel, while the main loop is responsible for running the Blynk process.

```
Import the threading and time libraries
Call the check_blynk_connection() function to ensure Blynk is
connected
Run the following functions concurrently (in separate threads):
    - monitor_light_sensor (automatic light sensor monitoring)
    - kontrol_suhu (automatic temperature monitoring)
    - toggle_timer (automatic LED timer control)
Start the main loop:
    While the program is running:
        Execute blynk.run() to handle commands from the Blynk
application
        Wait for 0.1 seconds
```

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```
If the user interrupts the program (KeyboardInterrupt):
    Display "Program stopped."
    Clean up all GPIO configurations
```

#### **Blynk Connection Check Function**

This function runs periodically to ensure that the Raspberry Pi remains connected to the Blynk server.

```
Function: check_blynk_connection
Display message:
    "Raspberry Pi successfully connected to Blynk 2.0!"
Run the check_blynk_connection function again after 10 seconds
```

#### **Blynk Application Settings**

The Blynk app is used to manually control LED 4. The Blynk app is set up by downloading the Blynk IoT app from the Play Store or App Store, then creating a new template on the blynk.cloud website by selecting the Raspberry Pi device and WiFi connection.

#define BLYNK\_TEMPLATE\_ID "TMPL6jYZMeLGv"
#define BLYNK\_TEMPLATE\_NAME "Home Automaton with Raspberry Pi3"
#define BLYNK\_AUTH\_TOKEN "T6YesasbjImjfknc3WR6He406pb0EU2d"

#### Figure 7. Bylnk token

After that, create a device from the template that has been created and copy the Auth Token as shown in Figure 7 to be entered into the Python program. In the Blynk application, add a Button widget associated with Virtual Pin V3 and set it in switch mode (ON/OFF) as shown in Figure 8.



Figure 8 Virtual pin & Blynk application display

The obtained Auth Token is entered into the Python code to connect the Raspberry Pi with Blynk. After the program is run on the Raspberry Pi, LED 4 can be controlled manually via the buttons available in the Blynk application. After all stages of the system development are completed, testing of the light control and monitoring functions is performed using the Blynk application, as shown in Figure 8.

### Testing

#### LED Testing 1 Based on LDR Sensor

This test was conducted to ensure that LED 1 can be controlled automatically based on ambient lighting conditions, i.e., only distinguishing between light and dark conditions. The testing process was carried out by adjusting the lighting around the LDR sensor and observing the response of LED 1. The test results are presented in Table 3 below:

Table 2 LED T Test Results					
<b>Environmental Conditions</b>	LED Status 1				
dark! LED On					
Bright! LED Off					

Table 2 shows the results of testing LED 1 controlled by a light sensor (LDR). Based on the test, when the LDR sensor detects dark environmental conditions, LED 1 will turn on automatically. Conversely, when the environmental conditions are bright, LED 1 will turn off. This shows that the system works well according to its designed function.

### LED Testing 2 Based on Temperature Sensor

This test aims to evaluate the response of LED 2 to changes in the ambient temperature. The temperature sensor used controls LED 2 with a specific temperature threshold. From the test results, LED 2 turns on when the ambient temperature exceeds  $30^{\circ}$ C and turns off when the temperature is below  $30^{\circ}$ C. Table 3 presents the test results obtained.



Table 2 LED 1 Test Results

temperature: 32 0c, humidity: 95%, Hot! LED Off



Table 3 shows the results of testing LED 2 controlled by the DHT11 temperature sensor. Based on the test, LED 2 only lights up when the sensor reads a temperature of  $27^{\circ}$ C. Meanwhile, at temperatures of  $30^{\circ}$ C and  $32^{\circ}$ C, LED 2 is off. This shows that the system is designed to turn on LED 2 only at temperatures below  $30^{\circ}$ C. This experiment indicates that the temperature control system has successfully functioned according to the designed logic, which is to activate the LED as an indicator when the temperature is within a certain range.

## LED Testing 3 Based on Time Scheduling

This test aims to ensure that LED 3 can turn on and off alternately at a predetermined time interval, namely 5 seconds on and 5 seconds off. The observation results using a stopwatch show that LED 3 successfully follows the specified time pattern with good accuracy. The test data can be seen in Table 4.

Status on Raspberry	LED Status 3
LED On for 5 seconds	
LED Off for 5 seconds	US

Table 4 LED 3 Test Results

Table 4 shows the results of testing LED 1 controlled by a light sensor (LDR). Based on the test, when the LDR sensor detects dark environmental conditions, LED 1 will turn on automatically. Conversely, when the environmental conditions are bright, LED 1 will turn off. This shows that the system works well according to its designed function.

### **Testing 4 LEDs via the Blynk Application**

This test was conducted to test the ability to control LED 4 remotely through the Blynk application connected to Raspberry Pi 3. The test results showed that the ON and OFF commands from the application were successfully received and responded to by the system. Table 5 summarizes the results of this test.



Table 5 LED 4 Test Results

Table 5 shows the test results of LED 4 controlled manually through the Blynk app. In this test, LED 4 can be turned on and off directly by the user using the virtual buttons available in the Blynk application on the smartphone. When the ON button is pressed the LED 4 will turn on, and when the OFF button is pressed the LED 4 will turn off. The response from the system takes place in real-time according to the commands given through the application. The results of this test show that the communication between the microcontroller system and the Blynk platform runs well and the manual control feature works as designed.

### **Overall System Testing**

After each LED is tested individually, an overall system test is conducted to ensure that all components can work in unison and in accordance with the conditions that have been designed. This test involves all control elements, namely the light sensor (LDR), temperature sensor (DHT11), automatic timer, and manual control through the Blynk application. The following are the overall system test results:

		Table 6 Overall Smarthome System Testing Results								
No	Light Condition	Temperature (°C)	Timer Status	Blynk Button	LED 1 (LDR)	LED 2 (Temp)	LED 3 (Timer)	LED 4 (Manual)		
1	Dark	32	Active (On 5s)	OFF	ON	OFF	ON	OFF		
2	Bright	30	Active (Off 5s)	ON	OFF	OFF	OFF	ON		
3	-	27	-	-	-	ON	-	-		

Table 6 Overall Smarthome System Testing Results

Based on the test results presented in Table 4.5, it can be concluded that the designed smarthome system has functioned properly and in accordance with the design objectives. LED 1 lights up when the environment is dark and will turn off automatically when detected as bright by the light sensor (LDR). LED 2 lights up only when the temperature is below 30°C and will turn off when the temperature reaches or exceeds that value, according to the data read by the DHT11 temperature sensor. LED 3 is controlled by an automatic timing system that sets the on and off cycle every 5 seconds alternately and repetitively without user intervention. Meanwhile, LED 4 functions well in receiving manual commands from the user through the Blynk application, both to activate and deactivate the LED in real-time. The results of this test prove that all system components can work simultaneously (parallel) without interruption, and the Raspberry Pi 3 is able to handle various input and output processes in multitasking with stability. Thus, this Internet of Things (IoT)-based smarthome system is feasible to be applied in everyday life, especially for controlling home electrical devices automatically or remotely.

The results of this study not only show that the system successfully controls LEDs according to light conditions, temperature, time, and manual commands, but also prove that the system has the flexibility of controlling other electronic equipment. In line with research [12] smarthomes function to control various kinds of electronic devices in the home. In this study, the LED acts as a load simulation, so technically this system can be applied to control household electrical devices such as room lights, fans, water pumps, or other equipment connected through relay modules. With the Raspberry Pi 3's ability to handle various inputs and outputs simultaneously and the support of remote control through the Blynk application, this system proves to have potential as an initial solution in the development of a smarthome that is more extensive, efficient, and responsive to user needs.

### Discussion

This research successfully designed and implemented an Internet of Things (IoT)-based smart home system by utilizing Raspberry Pi 3 as the control center. The system supports two operating modes, namely automatic and manual, through the Blynk application. In the test, the LEDs successfully turn on and off based on three automation scenarios namely light sensor (LDR), temperature sensor (DHT11), and time scheduling, and can be controlled manually remotely using a smartphone. The test results show that the system is able to perform control functions in four different scenarios with a fast and accurate response. The use of LDR sensors proved effective in detecting lighting conditions to automatically control LEDs, in line with the working principle of IoT-based light control systems as described by [13], which states that LDR can be used for automatic lighting optimization in smart home systems. Meanwhile, the DHT11 sensor is able to detect the ambient temperature in real-time and provide a control response to temperatures above a specified threshold, proving that this system can function adaptively to the environment.

This finding supports the IoT theory which states that devices can be interconnected through the internet network to perform functions automatically and efficiently without direct intervention from the user [1]. The implementation of Raspberry Pi as the main controller proved effective in managing data from various sensors and controlling output devices, as stated by [2] that Raspberry Pi has high integration capabilities for IoT-based automation systems. However, the advantage of this research lies in the integration of multi-sensors in one comprehensive automation system, which has not been widely raised in previous research. For example, [7] only designed a mobile-based light control system without sensor integration, while [5]focused more on home door security with RFID features.

The utilization of the Blynk application in this system makes it easy for users to control and monitor devices in real-time through an interactive graphical interface, in accordance with the findings [10] regarding the ease of developing IoT projects using the platform. The authentication feature through tokens in Blynk also guarantees the security of user access to the system. In addition, according to [14], combining IoT-based control with mobile applications allows the system to be more flexible in supporting scalable and secure automation. [15] also emphasized that a secure and cloud-based smart home system must prioritize access authentication and control scalability, which has been accommodated in this system through the use of Blynk tokens and wireless networks. Furthermore, research by [12] showed that the Raspberry Pi-based home

automation system has high reliability and is suitable for low-cost residential environments, supporting the contribution of this research to the development of smart homes that are modular, cost-effective, and easy to implement. The system is also a solution to the user's problem of efficiently controlling home appliances when outside the home, for example when forgetting to turn off electrical appliances.

### Conclusion

This research successfully designed and built a prototype of Internet of Things (IoT)-based smarthome system integrated with Blynk application, using Raspberry Pi 3 as the main control center. The system consists of a 4-channel relay module, LED, LDR light sensor, and DHT11 temperature sensor, each of which is controlled automatically or manually according to its function. The ability of the system to respond to predetermined test parameters, namely light intensity (light/dark), ambient temperature (with a threshold of 30°C), automatic timing (5 seconds on and 5 seconds off), and manual control through the Blynk application. The test results show that all functions are successfully executed: LED 1 responds to light conditions, LED 2 responds to temperature, LED 3 follows the automatic time interval, and LED 4 responds to commands from the application in real-time. This research also opens up opportunities for the application of cost-effective, flexible, and easy-to-implement home control systems widely, especially to improve energy efficiency and user comfort in daily life. The developed system also provides a basis for further development towards a more complex and integrated smart home system, both in terms of functionality and scalability. This is an important first step towards transforming conventional homes into smart homes that are adaptive to environmental conditions and user needs.

#### Acknowledge

This research is expected to be developed further so that in the future it can be implemented on a larger scale, so that the smart home system designed can be applied in real life in residential and other building environments.

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